Accelerating the resolution of sovereign debt models using an endogenous grid method

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CENTRE POUR LA RECHERCHE ECONOMIQUE ET SES APPLICATIONS

Summary

- Endogenous default models don't benefit from advanced DSGE resolution techniques (FOC not enough: value function needed, regime switching)
- State-of-the art: slow value function iteration (VFI); equivalent to far away finite horizon
- Idea: use endogenous grid method (EGM) instead
- Features of this method:
 - Use fixed grid for control variable
 - Endogenously deduce grid for *state* variable
 - Strength: uses FOC ⇒ no maximization (but nonlinear solver)
- ► Extension to sovereign debt models: grids for both state and control variables need be endogenous ⇒ 2EGM
- 2EGM much faster than VFI for similar accuracy



State of the art

The doubly endogenous grid method (2EGM)

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State of the art

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Model setup

- Tradition of Eaton and Gersovitz (1981), Cohen and Sachs (1986)
- Sovereign country (with representative agent) produces and consumes
- Production is an exogenous stochastic stream
- Difference between production and consumption financed on international markets
 - \Rightarrow accumulation of a stock of (short-term) external debt
- The country can make the strategic decision to default
- Default implies financial autarky and cost on output
- Anticipating default, international markets may impose a (model-consistent) risk premium or ration the country

Output is non stationary, with AR(1) shocks to the stochastic growth trend:

$$\tilde{y}_t = g_t \, \tilde{y}_{t-1}$$

$$\log(g_t) = (1 - \rho_g) \left(\log(\mu_g) - \frac{\sigma_g^2}{2(1 - \rho_g^2)} \right) + \rho_g \log(g_{t-1}) + \varepsilon_t^g$$

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where $\rho_g \in [0, 1)$, $\varepsilon_t^g \rightsquigarrow \mathcal{N}(0, \sigma_g^2)$

Agent interactions

If the sovereign repays:

$$\tilde{c}_t^G = \tilde{y}_t + \tilde{a}_t - \tilde{q}(\tilde{y}_t, \tilde{a}_{t+1})\tilde{a}_{t+1}$$
$$\tilde{V}^G(\tilde{a}_t, \tilde{y}_t) = \max_{\tilde{a}_{t+1}} \left\{ u(\tilde{c}_t^G) + \beta \mathbb{E}_t V(\tilde{a}_{t+1}, \tilde{y}_{t+1}) \right\}$$

If the sovereign defaults:

$$\begin{split} \tilde{c}_t^B &= \tilde{y}_t^B = (1 - \delta) \tilde{y}_t \\ \tilde{V}^B(\tilde{y}_t) &= u(\tilde{c}_t^B) + \beta \, \mathbb{E}_t \left[(1 - \lambda) \tilde{V}^B(\tilde{y}_{t+1}) + \lambda \, \tilde{V}(0, \tilde{y}_{t+1}) \right] \end{split}$$

Optimal choice between repayment and default:

$$egin{aligned} & ilde{V}(ilde{a}_t, ilde{y}_t) = \max\{ ilde{V}^G(ilde{a}_t, ilde{y}_t), ilde{V}^B(ilde{y}_t)\}\ & ilde{D}(ilde{a}_t, ilde{y}_t) = \mathbbm{1}_{ ilde{V}^G(ilde{a}_t, ilde{y}_t) < ilde{V}^B(ilde{y}_t)} \end{aligned}$$

Investors' zero profit condition (pins down the risk-adjusted interest rate):

$$(1+r)q(\tilde{y}_t,\tilde{a}_{t+1}) = \mathbb{E}_t \left[1 - \tilde{D}(\tilde{a}_{t+1},\tilde{y}_{t+1}) \right]$$

Detrended model

Detrending factor:

$$\tilde{\Gamma}_t = \mu_g \tilde{y}_{t-1}$$

► In particular:

$$y_t = \frac{g_t}{\mu_g}$$

Detrended equations:

$$V(a_t, y_t) = \max\{V^G(a_t, y_t), V^B(y_t)\}$$

$$V^{G}(a_{t}, y_{t}) = \max_{a_{t+1}} \left\{ u(y_{t} + a_{t} - q(y_{t}, a_{t+1})a_{t+1}g_{t}) + \beta g_{t}^{1-\gamma} \mathbb{E}_{t} V(a_{t+1}, y_{t+1}) \right\}$$

$$V^{B}(y_{t}) = u((1-\lambda)y_{t}) + \beta g_{t}^{1-\gamma} \mathbb{E}_{t} \left[(1-\lambda)V^{B}(y_{t+1}) + \lambda V(0, y_{t+1}) \right]$$
$$D(a_{t}, y_{t}) = \mathbb{1}_{V^{G}(a_{t}, y_{t}) < V^{B}(y_{t})}$$
$$(1+r)q(y_{t}, a_{t+1}) = \mathbb{E}_{t} \left[1 - D(a_{t+1}, y_{t+1}) \right]$$



State of the art

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Value Function Iteration (VFI)

- 1. Define an interpolation grid $(a_i, y_j)_{(i,j) \in I \times J}$
- 2. Let n = 0, initialize $\hat{V}^{G,(0)}$ and $\hat{V}^{B,(0)}$
- 3. At each point of the grid, compute $\hat{V}^{G,(n+1)}$ and $\hat{V}^{B,(n+1)}$ by

$$\begin{split} \hat{V}^{G,(n+1)}(a_i, y_j) &= \max_{a'} \{ u(y_j + a_i - \hat{q}^{(n+1)}(y_j, a')a'g_j) + \beta g_j^{1-\gamma} \int \hat{V}^{(n)}(a', y') \mathrm{d}F(y'|y_j) \} \\ \hat{V}^{B,(n+1)}(y_j) &= u((1-\delta)y_j) + \beta g_j^{1-\gamma} \int \left[(1-\lambda)\hat{V}^{B,(n)}(y') + \lambda \hat{V}^{(n)}(0, y') \right] \mathrm{d}F(y'|y_j) \end{split}$$

Involves the computation of an integral and a function maximization. Also requires computation of price function $\hat{q}^{(n+1)}$

4. If $\hat{V}^{(n+1)}$ close to $\hat{V}^{(n)}$, stop. Otherwise, let n = n+1 and goto 3

Implementations of VFI

- Discrete State Space (DSS): no interpolation, discretize the state space, the control space and the law of motion of growth
- Alternatively, interpolation with cubic splines
- Hatchondo et al. (2010):
 - DSS is both inefficient and imprecise compared to cubic splines

- some papers have qualitatively wrong results because of DSS
- VFI is slow because it needs an optimization at every point of the grid, at every iteration



State of the art

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Overview of EGM

- Introduced by Carroll (2006)
- Extended by Fernandez & Villaverde (2007)
- Backward computation of value function, as in VFI
- But uses FOC (Euler equation) instead of objective maximization (Bellman equation)
- As a consequence, much faster
- Euler equation of the canonical model:

$$u'(c_t)\left[q(y_t, a_{t+1}) + a_{t+1}\frac{\partial q}{\partial a_{t+1}}(y_t, a_{t+1})\right]g_t = \beta g_t^{1-\gamma} \mathbb{E}_t \frac{\partial V}{\partial a_{t+1}}(a_{t+1}, y_{t+1})$$

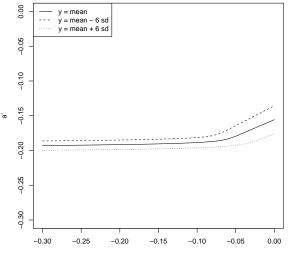
where $c_t = y_t + a_t - q(y_t, a_{t+1})a_{t+1}g_t$

EGM on canonical model

- Define a fixed grid for tomorrow's assets (a'_i)_{i∈I}, and one for today's output (y_j)_{j∈J}
- 2. Let n = 0. Choose initial values for $\hat{V}^{G,(0)}$ and $\hat{V}^{B,(0)}$. Choose initial grid, $(a_{ij}^{(0)}, y_j)_{(i,j)\in I \times J}$ for $\hat{V}^{G,(0)}$. The grid $a_{ij}^{(n)}$ will vary, hence the name of EGM
- 3. Compute $\hat{V}^{B,(n+1)}$ as in VFI (backward iteration)
- 4. Compute $\hat{V}^{G,(n+1)}$: for every (a'_i, y_j) , use Euler equation to find c consistent with a'_i (involves a nonlinear solver and two numerical differentiations but *no maximization*)
- 5. Deduce today's assets $a_{ij}^{(n+1)}$ with resource constraint, and deduce $\hat{V}^{G,(n+1)}$ at $(a_{ij}^{(n+1)}, y_j)$
- 6. If $\hat{V}^{(n+1)}$ close to $\hat{V}^{(n)}$, stop. Otherwise, set n = n+1 and goto 3

Why EGM fails on canonical sovereign debt model

Choice function for tomorrow's level of debt, given today's level



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2EGM

- Idea: make the grid for tomorrow's assets also endogenous
- Iteratively adapt that grid so that it converges towards ergodic set
- More precisely, find upper and lower limits for tomorrow's assets, so that today's assets fall in the endogenous grid of previous period
- Implementation: dichotomy-based algorithm
- Grid for both today's and tomorrow's assets is endogenous, hence the 2EGM name
- Extra bonus: approximation of the solution only computed on ergodic set



State of the art

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Comparison devices

- Comparison dimensions: speed, ease of implementation, accuracy (moments, average Euler errors)
- On the canonical model
- And on the "trembling times" model of Cohen and Villemot (2012)
 - Growth has a Brownian and a Poisson component
 - Poisson component = exogenous risk of being hit by a confidence shock which has real negative consequences

- Confidence can be restored if no default during crisis
 markets act like a "trembling hand"
- ► Recovery value for investors in case of default ⇒ raises sustainable debt-levels
- State space of dim. 3, shocks of dim. 2

Comparison results

| Model | Canonical | | Trembling | |
|---|------------------|------------|-----------------|------------------|
| Solution characteristics | | | | |
| Method | VFI | 2EGM | VFI | 2EGM |
| Grid points | 15 	imes 30 | 15	imes 30 | 10 ³ | 10 ³ |
| Convergence criterion | 10 ⁻⁶ | 10^{-6} | $10^{-1.7}$ | 10 ⁻³ |
| Lines of $C++$ code | 1,000 | 1,080 | 1,423 | 1,525 |
| Solution time | | | | |
| Single thread | 54.4s | 5.8s | 3,588s | 413s |
| 8 threads | 15.9s | 3.1s | 1,396s | 195s |
| Moments | | | | |
| Rate of default (%, per year) | 0.86 | 0.86 | 1.24 | 2.50 |
| Mean D/Q (%, annualized) | 4.68 | 4.68 | 38.58 | 38.17 |
| <i>Euler errors (in</i> log ₁₀ <i>units)</i> | | | | |
| Mean | -4.38 | -4.20 | -1.99 | -2.08 |
| Max | -3.47 | -3.39 | -0.98 | -0.46 |

Conclusion

- 2EGM faster than VFI by a factor between 5 and 10, for same accuracy level
- Same complexity of implementation
- Future work:
 - Merging of DSGE elements (following Mendoza and Yue, 2012)

Computationally: sparse grid methods

Thanks for your attention!

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