

# Accelerating the resolution of sovereign debt models using an endogenous grid method

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CENTRE POUR LA RECHERCHE ECONOMIQUE ET SES APPLICATIONS

# Summary

- ▶ Endogenous default models don't benefit from advanced DSGE resolution techniques (FOC not enough: value function needed, regime switching)
- ▶ State-of-the art: slow value function iteration (VFI); equivalent to far away finite horizon
- ▶ Idea: use endogenous grid method (EGM) instead
- ▶ Features of this method:
  - ▶ Use fixed grid for *control* variable
  - ▶ Endogenously deduce grid for *state* variable
  - ▶ Strength: uses FOC  $\Rightarrow$  no maximization (but nonlinear solver)
- ▶ Extension to sovereign debt models: grids for both state and control variables need be endogenous  $\Rightarrow$  2EGM
- ▶ 2EGM much faster than VFI for similar accuracy

# Outline

A canonical sovereign debt model

State of the art

The doubly endogenous grid method (2EGM)

Assessment of VFI and 2EGM

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# Model setup

- ▶ Tradition of Eaton and Gersovitz (1981), Cohen and Sachs (1986)
- ▶ Sovereign country (with representative agent) produces and consumes
- ▶ Production is an exogenous stochastic stream
- ▶ Difference between production and consumption financed on international markets  
⇒ accumulation of a stock of (short-term) external debt
- ▶ The country can make the strategic decision to default
- ▶ Default implies financial autarky and cost on output
- ▶ Anticipating default, international markets may impose a (model-consistent) risk premium or ration the country

# Output process

Output is non stationary, with AR(1) shocks to the stochastic growth trend:

$$\tilde{y}_t = g_t \tilde{y}_{t-1}$$
$$\log(g_t) = (1 - \rho_g) \left( \log(\mu_g) - \frac{\sigma_g^2}{2(1 - \rho_g^2)} \right) + \rho_g \log(g_{t-1}) + \varepsilon_t^g$$

where  $\rho_g \in [0, 1)$ ,  $\varepsilon_t^g \rightsquigarrow \mathcal{N}(0, \sigma_g^2)$

## Agent interactions

- ▶ If the sovereign repays:

$$\tilde{c}_t^G = \tilde{y}_t + \tilde{a}_t - \tilde{q}(\tilde{y}_t, \tilde{a}_{t+1})\tilde{a}_{t+1}$$
$$\tilde{V}^G(\tilde{a}_t, \tilde{y}_t) = \max_{\tilde{a}_{t+1}} \left\{ u(\tilde{c}_t^G) + \beta \mathbb{E}_t V(\tilde{a}_{t+1}, \tilde{y}_{t+1}) \right\}$$

- ▶ If the sovereign defaults:

$$\tilde{c}_t^B = \tilde{y}_t^B = (1 - \delta)\tilde{y}_t$$
$$\tilde{V}^B(\tilde{y}_t) = u(\tilde{c}_t^B) + \beta \mathbb{E}_t \left[ (1 - \lambda)\tilde{V}^B(\tilde{y}_{t+1}) + \lambda \tilde{V}(0, \tilde{y}_{t+1}) \right]$$

- ▶ Optimal choice between repayment and default:

$$\tilde{V}(\tilde{a}_t, \tilde{y}_t) = \max\{\tilde{V}^G(\tilde{a}_t, \tilde{y}_t), \tilde{V}^B(\tilde{y}_t)\}$$
$$\tilde{D}(\tilde{a}_t, \tilde{y}_t) = \mathbb{1}_{\tilde{V}^G(\tilde{a}_t, \tilde{y}_t) < \tilde{V}^B(\tilde{y}_t)}$$

- ▶ Investors' zero profit condition (pins down the risk-adjusted interest rate):

$$(1 + r)q(\tilde{y}_t, \tilde{a}_{t+1}) = \mathbb{E}_t \left[ 1 - \tilde{D}(\tilde{a}_{t+1}, \tilde{y}_{t+1}) \right]$$

## Detrended model

- ▶ Detrending factor:

$$\tilde{\Gamma}_t = \mu_g \tilde{y}_{t-1}$$

- ▶ In particular:

$$y_t = \frac{g_t}{\mu_g}$$

- ▶ Detrended equations:

$$V(a_t, y_t) = \max\{V^G(a_t, y_t), V^B(y_t)\}$$

$$V^G(a_t, y_t) = \max_{a_{t+1}} \left\{ u(y_t + a_t - q(y_t, a_{t+1})a_{t+1} g_t) \right. \\ \left. + \beta g_t^{1-\gamma} \mathbb{E}_t V(a_{t+1}, y_{t+1}) \right\}$$

$$V^B(y_t) = u((1-\lambda)y_t) + \beta g_t^{1-\gamma} \mathbb{E}_t \left[ (1-\lambda)V^B(y_{t+1}) + \lambda V(0, y_{t+1}) \right]$$

$$D(a_t, y_t) = \mathbb{1}_{V^G(a_t, y_t) < V^B(y_t)}$$

$$(1+r)q(y_t, a_{t+1}) = \mathbb{E}_t [1 - D(a_{t+1}, y_{t+1})]$$



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# Value Function Iteration (VFI)

1. Define an interpolation grid  $(a_i, y_j)_{(i,j) \in I \times J}$
2. Let  $n = 0$ , initialize  $\hat{V}^{G,(0)}$  and  $\hat{V}^{B,(0)}$
3. At each point of the grid, compute  $\hat{V}^{G,(n+1)}$  and  $\hat{V}^{B,(n+1)}$  by

$$\hat{V}^{G,(n+1)}(a_i, y_j) = \max_{a'} \{ u(y_j + a_i - \hat{q}^{(n+1)}(y_j, a') a' g_j) + \beta g_j^{1-\gamma} \int \hat{V}^{(n)}(a', y') dF(y'|y_j) \}$$

$$\hat{V}^{B,(n+1)}(y_j) = u((1-\delta)y_j) + \beta g_j^{1-\gamma} \int [(1-\lambda)\hat{V}^{B,(n)}(y') + \lambda \hat{V}^{(n)}(0, y')] dF(y'|y_j)$$

Involves the computation of an integral and a function maximization. Also requires computation of price function  $\hat{q}^{(n+1)}$

4. If  $\hat{V}^{(n+1)}$  close to  $\hat{V}^{(n)}$ , stop. Otherwise, let  $n = n + 1$  and goto 3

# Implementations of VFI

- ▶ Discrete State Space (DSS): no interpolation, discretize the state space, the control space and the law of motion of growth
- ▶ Alternatively, interpolation with cubic splines
- ▶ Hatchondo et al. (2010):
  - ▶ DSS is both inefficient and imprecise compared to cubic splines
  - ▶ some papers have *qualitatively* wrong results because of DSS
- ▶ VFI is slow because it needs an optimization at every point of the grid, at every iteration

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# Overview of EGM

- ▶ Introduced by Carroll (2006)
- ▶ Extended by Fernandez & Villaverde (2007)
- ▶ Backward computation of value function, as in VFI
- ▶ But uses FOC (Euler equation) instead of objective maximization (Bellman equation)
- ▶ As a consequence, much faster
- ▶ Euler equation of the canonical model:

$$u'(c_t) \left[ q(y_t, a_{t+1}) + a_{t+1} \frac{\partial q}{\partial a_{t+1}}(y_t, a_{t+1}) \right] g_t = \beta g_t^{1-\gamma} \mathbb{E}_t \frac{\partial V}{\partial a_{t+1}}(a_{t+1}, y_{t+1})$$

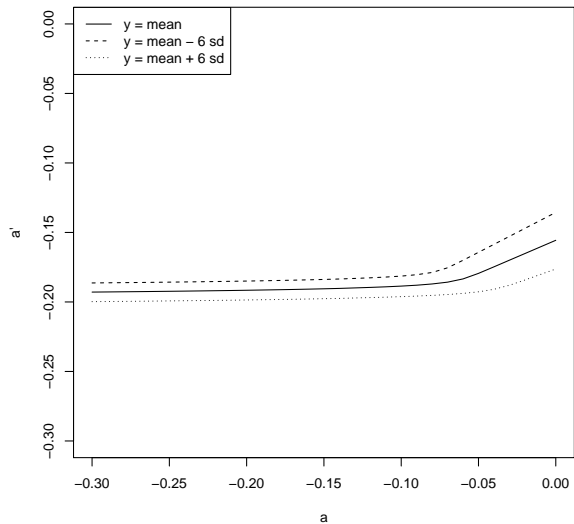
where  $c_t = y_t + a_t - q(y_t, a_{t+1})a_{t+1}g_t$

## EGM on canonical model

1. Define a fixed grid for *tomorrow's* assets  $(a'_i)_{i \in I}$ , and one for today's output  $(y_j)_{j \in J}$
2. Let  $n = 0$ . Choose initial values for  $\hat{V}^{G,(0)}$  and  $\hat{V}^{B,(0)}$ .  
Choose initial grid,  $(a_{ij}^{(0)}, y_j)_{(i,j) \in I \times J}$  for  $\hat{V}^{G,(0)}$ . The grid  $a_{ij}^{(n)}$  will vary, hence the name of EGM
3. Compute  $\hat{V}^{B,(n+1)}$  as in VFI (backward iteration)
4. Compute  $\hat{V}^{G,(n+1)}$ : for every  $(a'_i, y_j)$ , use Euler equation to find  $c$  consistent with  $a'_i$  (involves a nonlinear solver and two numerical differentiations but *no maximization*)
5. Deduce today's assets  $a_{ij}^{(n+1)}$  with resource constraint, and deduce  $\hat{V}^{G,(n+1)}$  at  $(a_{ij}^{(n+1)}, y_j)$
6. If  $\hat{V}^{(n+1)}$  close to  $\hat{V}^{(n)}$ , stop. Otherwise, set  $n = n + 1$  and goto 3

# Why EGM fails on canonical sovereign debt model

Choice function for tomorrow's level of debt, given today's level



## 2EGM

- ▶ Idea: make the grid for tomorrow's assets also endogenous
- ▶ Iteratively adapt that grid so that it converges towards ergodic set
- ▶ More precisely, find upper and lower limits for tomorrow's assets, so that today's assets fall in the endogenous grid of previous period
- ▶ Implementation: dichotomy-based algorithm
- ▶ Grid for both today's and tomorrow's assets is endogenous, hence the 2EGM name
- ▶ Extra bonus: approximation of the solution only computed on ergodic set



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# Comparison devices

- ▶ Comparison dimensions: speed, ease of implementation, accuracy (moments, average Euler errors)
- ▶ On the canonical model
- ▶ And on the “trembling times” model of Cohen and Villemot (2012)
  - ▶ Growth has a Brownian and a Poisson component
  - ▶ Poisson component = exogenous risk of being hit by a confidence shock which has real negative consequences
  - ▶ Confidence can be restored if no default during crisis  
⇒ markets act like a “trembling hand”
  - ▶ Recovery value for investors in case of default  
⇒ raises sustainable debt-levels
  - ▶ State space of dim. 3, shocks of dim. 2

## Comparison results

<i>Model</i>	<i>Canonical</i>		<i>Trembling</i>	
<i>Solution characteristics</i>				
Method	VFI	2EGM	VFI	2EGM
Grid points	$15 \times 30$	$15 \times 30$	$10^3$	$10^3$
Convergence criterion	$10^{-6}$	$10^{-6}$	$10^{-1.7}$	$10^{-3}$
Lines of C++ code	1,000	1,080	1,423	1,525
<i>Solution time</i>				
Single thread	54.4s	5.8s	3,588s	413s
8 threads	15.9s	3.1s	1,396s	195s
<i>Moments</i>				
Rate of default (% , per year)	0.86	0.86	1.24	2.50
Mean $D/Q$ (% , annualized)	4.68	4.68	38.58	38.17
<i>Euler errors (in <math>\log_{10}</math> units)</i>				
Mean	-4.38	-4.20	-1.99	-2.08
Max	-3.47	-3.39	-0.98	-0.46

# Conclusion

- ▶ 2EGM faster than VFI by a factor between 5 and 10, for same accuracy level
- ▶ Same complexity of implementation
- ▶ Future work:
  - ▶ Merging of DSGE elements (following Mendoza and Yue, 2012)
  - ▶ Computationally: sparse grid methods

Thanks for your attention!

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